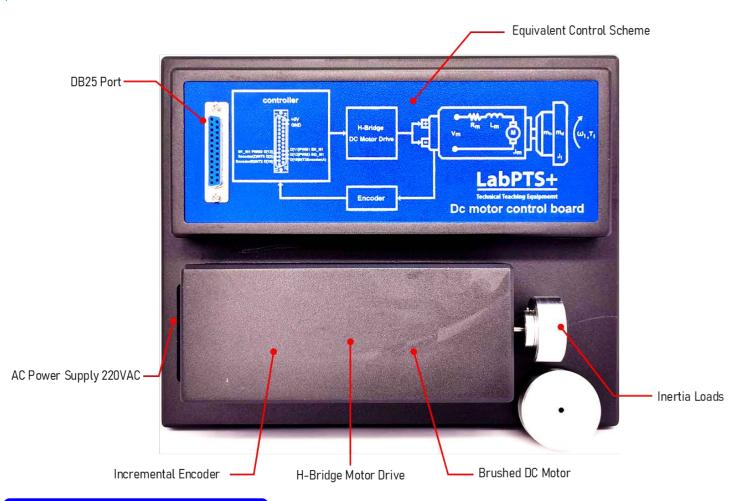


BRUSHED DC MOTOR CONTROL SYSTEM LAB KITS V1.0

FOR EDUCATION IN EMBEDDED CONTROL SYSTEM FIELDS



FEATURE DETAIL

- Brushed DC Motor Control System Lab Kits V1.0 is designed as add-on for co-working with the xMCU development board V1.0 so suitable undergraduate degree or vocational/diploma education.
- Cover the lesson comprehensive to Open loop control, Closed loop control such as Conventional PID control, Fuzzy Logic Control.
- Easy to use, the pin's function modules are reserved by not wiring so just the coding and then upload into development board.
- Support for Arduino IDE, LabVIEW, MATLAB/Simulink Software development and other (due to microcontrollers/processing unit series).
- Learning about principle of electromechanical machine behavior.
- The permanent magnet has high-power and high-speed properties.
- The package is made from PVC material so portable, compact size, lightweight and dimension 250x200x50 mm.

ACCESSORIES LAB KITS

- Brushed DC Motor Control System Lab Kits V1.0.
- AC Power Cable.
- Inertia Loads.

- Arduino IDE Software (Open source).
- C-Code Example (Only Arduino).
- Worksheet Document.



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SYSTEM CONFIGURATIONS

Module Interface	Description	Remark
Brushed DC Motor		
- Model	CHR-3162 ABHL DC motor	
- Construction	Permanent magnet	
- Commutation	Brush	
- Continuous Current	110-350 mA	
- Torque	100-200 g.cm	
- Operating Voltage	12 VDC	
- Speed	4,000 rpm	N/A
- Output Shaft Length	19 mm.	
- Shaft Diameter	3 mm.	
- Motor Diameter	31 mm.	
- Applications	Robots, mechanical equipment, automatic rotating equipment, etc.	
Brushed DC Motor Drive		
- Туре	Dual H-bridge motor drive (Bidirectional control)	
- Operating Mode	Stop, forward, reverse	
- IC Drive	L298	N/A
- Protection	Over temperature protection	
- Operating Supply Voltage	Up to 35 VDC	
- DC Current	Total up to 3 A (only single motor)	
- Others	Integrated 5VDC power regulator	
Encoder		
- Туре	AB dual phase incremental encoder	
- Pulse outputs of rotation	Basic pulse 11 PPR	
- Power Supply Voltage	3.3/5.0 VDC	
- Basic Function	With the pull up shaping resister, the single-ship microcomputer can be used	
- Encoder Interface Type	PH2.0 (standard wiring)	
- Output Signal Type	Square wave AB phase	
- Response Frequency	100 kHz	
- Basic Pulse Number	11 PPR	
- Poles of Magnetic Ring	22 Poles (11 pairs of poles)	
Inertia Loads		
- Material	Aluminum/Iron (2 pieces)	N/A